

Physics 202, Lecture 14

Today's Topics

- **Sources of the Magnetic Field (Ch. 30)**
 - **Review: Biot-Savart Law, Ampere's Law**
 - **Displacement Current: Ampere-Maxwell Law**
 - **Magnetism in Matter**
 - **Maxwell's Equations (prelude)**

- **Faraday's Law of Induction (Ch. 31)**

Homework #6: due 10/22 ,10 PM.

Optional reading quiz: due 10/19, 7 PM

Sources of **E** and **B** Fields: An overview

- **Sources of electric fields:**
 - **Static electric charges: Coulomb's Law/Gauss's Law**
 - **Change of **B** field (magnetic flux): Faraday's Law**
(today and next lectures)

 - **Sources of magnetic fields:**
 - **Electric current: Biot-Savart Law/Ampere's Law**
 - **Change of **E** field (electric flux): Ampere-Maxwell Law**
(today)
- summarized in Maxwell's Equations (later today)

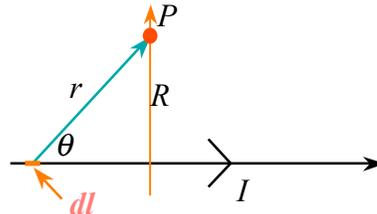
Magnetic Forces and Fields

Magnetic Force: $\vec{F} = \int I d\vec{l} \times \vec{B}$

Magnetic Field:

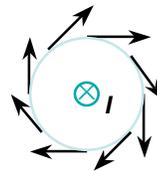
Biot-Savart Law:

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{I d\vec{l} \times \hat{r}}{r^2}$$



Ampere's Law:

$$\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{enclosed}$$



$\mu_0 = 4\pi \times 10^{-7} \text{ T}\cdot\text{m/A}$:
permeability of free space

Direction of integration along path: use right-hand rule

Magnetic Fields: Examples (Biot-Savart)

□ Current loop, distance x on loop axis (radius R):

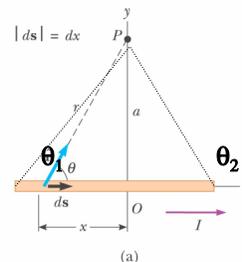
$$B_x = \frac{\mu_0 I R^2}{2(x^2 + R^2)^{3/2}} \quad B_{center} = \frac{\mu_0 I}{2R}$$

□ Center of arc (radius R, angle θ): $B_{center} = \frac{\mu_0 I \theta}{4\pi R}$

□ Straight wire: finite length

$$B = \frac{\mu_0 I}{4\pi a} (\cos \theta_1 - \cos \theta_2)$$

infinite wire: $B = \frac{\mu_0 I}{2\pi a}$

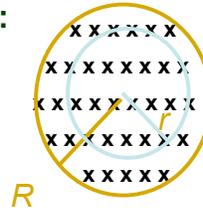


Magnetic Fields: Examples (Ampere's Law)

- Infinite wire: Inside wire, radius R :

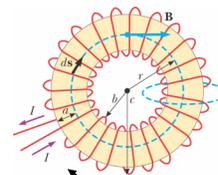
$$B = \frac{\mu_0 I}{2\pi r}$$

$$B = \frac{\mu_0 I r}{2\pi R^2}$$



- Axial field inside toroid (N turns)

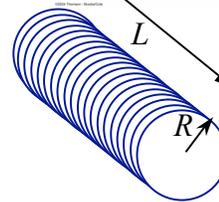
$$B_\phi = \frac{\mu_0 N I}{2\pi r}$$



- B field inside long solenoid ($L \gg R$)
(n turns/length)

$$B = \mu_0 n I$$

Uniform field!



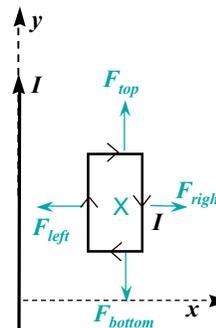
Question

- A current I flows in the $+y$ direction in an infinite wire; a current I also flows in loop. What is F_x , the net force on the loop in the x -direction?

(a) $F_x < 0$

(b) $F_x = 0$

(c) $F_x > 0$



- Recall: net force on a current loop in a uniform B-field is zero -- but the B-field of an infinite wire is **not uniform!**
- Forces cancel on the top and bottom of the loop.
- Forces **do not** cancel on the left and right sides of the loop.

- The left segment is in a larger magnetic field than the right:

$$F_{\text{left}} > F_{\text{right}}$$

Magnetic Field Generated by Varying **E** Field

□ General Form of Ampere's Law

→ Ampere-Maxwell Law:

$$\Phi_E \equiv \int \vec{E} \cdot d\vec{A}$$

$$\oint_{\text{any closed path}} \vec{B} \cdot d\vec{s} = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt} = \mu_0 (I + I_d)$$

→ Changing electric field also generates a B field!

displacement current

Example: charging capacitor

Text: problem 30.37

$$I_d \equiv \epsilon_0 \frac{d\Phi_E}{dt}$$

Magnetism in Matter

The B field produced along the axis of a circular loop (radius R) by a current I is:

$$\vec{B} \approx \frac{\mu_0 \mu}{2\pi z^3} \hat{z} \quad \text{typical dipole behaviour}$$

μ is the magnetic moment = $I \cdot \text{area}$

and $z \gg R$

Materials are composed of particles that have magnetic moments -- (negatively charged electrons circling around the positively charged nucleus).

orbital angular momentum
spin angular momentum

(quantum mechanics)

$$\mu_B = \frac{e\hbar}{2m_e} = 9.27 \times 10^{-24} \frac{J}{T}$$

Bohr magneton

Magnetization

Text examples:
Ch 30, #41,43

Apply external B field B_0 . Field is changed within materials by these magnetic moments.

Magnetization: total magnetic moment per unit volume $\vec{M} \equiv \frac{\vec{\mu}_{total}}{V}$

The B field in the material is $\vec{B} = \vec{B}_0 + \mu_0 \vec{M}$

Define H (magnetic field strength): $\vec{B} = \mu_0 (\vec{H} + \vec{M})$
($\vec{H} = \vec{B}_0 / \mu_0$)

Magnetic susceptibility: $\vec{M} = \chi \vec{H}$

$\vec{B} = \mu \vec{H} = \mu_0 (1 + \chi) \vec{H}$ "permeability" $\mu (= \kappa_m \mu_0)$

Magnetic Materials

Materials are classified by magnetic susceptibilities:

- **Paramagnetic** (aluminum, tungsten, oxygen,...)
Atomic magnetic dipoles line up with the field, increasing it.
Only small effects due to thermal randomization: $\chi \sim +10^{-5}$
- **Diamagnetic** (gold, copper, water,...as well as superconductors)
 - Applied field induces an opposing field; usually very weak $\chi \sim -10^{-5}$
- **Ferromagnetic** (iron, cobalt, nickel,...)
 - Dipoles prefer to line up with the applied field (similar to paramagnetic), but tend to all line up the same way due to collective effects:
very strong enhancements $\chi \sim +10^{+3} - 10^{+5}$

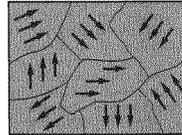
Magnetic susceptibility temperature dependent
(above range of typical values given at T=20 C)

Ferromagnets

- Dipoles tend to strongly align over small patches – “domains” (even w/o external magnetic field). With external field, the domains align to produce a large net magnetization.

“Soft” ferromagnets

Domains re-randomize when magnetic field is removed

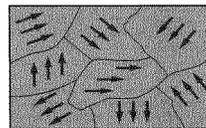


Magnetic Domains

•“Hard” ferromagnets

- Domains persist even when the field is removed
- “Permanent” magnets
- Domains may be aligned in a different direction in a new external field
- Domains may be re-randomized by sudden physical shock
- If temperature is raised above “Curie point” (770 °C for iron), domains will also randomize (like a paramagnet)

- Applied field aligns almost all the dipoles – and the “domains”. Magnetization is then “saturated”: no further increase.



Magnetic Domains

• “Hard” ferromagnets:

- Domains can persist even when the field is removed
- “Permanent” magnets
 - Domains may be aligned in different directions by changing the applied field.....

A “memory” effect that requires a large reverse field to significantly change the magnetization of the object: “hysteresis”.

Maxwell's Equations: Prelude

Gauss's Law: Electric Fields $\oint \vec{E} \cdot d\vec{A} = \frac{q_{\text{enclosed}}}{\epsilon_0}$

Gauss's Law: Magnetic Fields $\oint \vec{B} \cdot d\vec{A} = 0$

Ampere-Maxwell: $\oint \vec{B} \cdot d\vec{s} = \mu_0 I_{\text{enclosed}} + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$

What about $\oint \vec{E} \cdot d\vec{s}$?

Recall definition of flux: $\Phi_E = \int \vec{E} \cdot d\vec{A}$ $\Phi_M = \int \vec{B} \cdot d\vec{A}$

The Path Integral of the E field

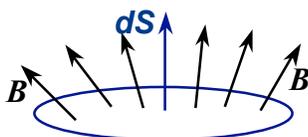
Recall in electrostatics: Coulomb force conservative

$$\oint \vec{E} \cdot d\vec{s} = 0$$

define electrostatic potential: $V_b - V_a = -\int_a^b \vec{E} \cdot d\vec{s}$

But in the presence of moving charges (B fields):

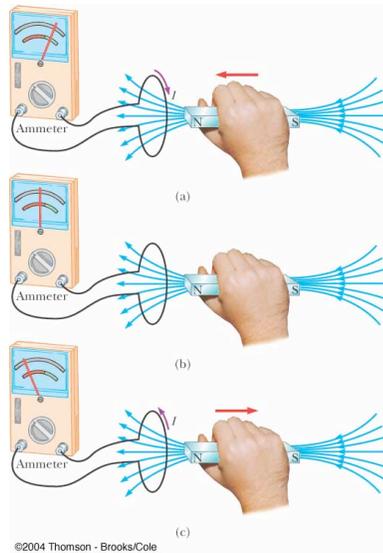
new contribution to E field, with



$$\epsilon = \oint \vec{E}_{NC} \cdot d\vec{s} \neq 0$$

Induced emf! (Faraday)

Emf and Change of Magnetic Flux



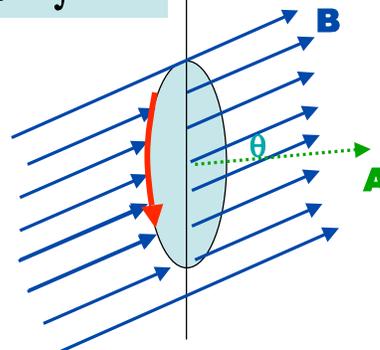
Also: battery-less flashlight

Faraday's Law of Induction

- Emf induced in a “circuit” is proportional to the time rate of **change of magnetic flux** through the “circuit”.

$$\mathcal{E} = - \frac{d\Phi_B}{dt}$$

$$\Phi_B = \int \vec{B} \cdot d\vec{A}$$

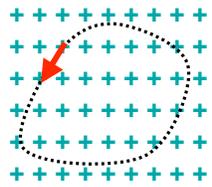


“Circuit”: any closed path
(does not have to be a
real conducting circuit)

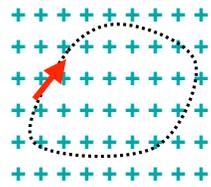
Direction: **opposes** change in magnetic flux (**Lenz's Law**)

Exercises: Determine Direction of Induced Emf

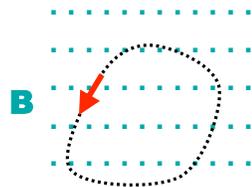
□ Indicate the direction of emf in the following cases:



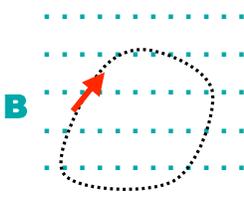
|B| increases



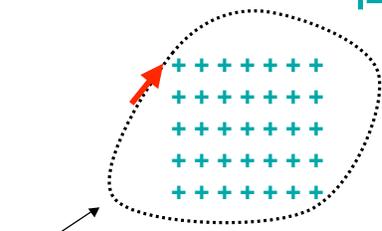
|B| decreases



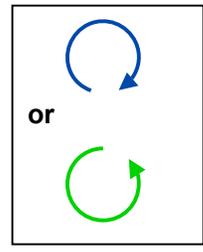
|B| decreases



|B| increases



path outside B **|B| decreases**



Methods to Change Electric Flux

$$\mathcal{E} = -\frac{d\Phi_B}{dt} = -\frac{d(BA\cos\theta)}{dt}$$

uniform B

Change of $\Phi_B \rightarrow$ emf

- To change Φ_B :
 - Change B \rightarrow emf produced by an induced E field
 - Change A \rightarrow motional emf
 - Change $\theta \rightarrow$ motional emf
 - Combination of above

Example: Ch. 31, #1