

IceCube
PMT HV Base Board
Engineering Requirements Document (ERD)

Version 2.2e (Draft)

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1 GENERAL

1.1 Scope

This IceCube Engineering Requirements Document (ERD) specifies the physical, functional and performance requirements for the PMT High Voltage Base circuit board.

1.2 Purpose

This requirement documentation shall be applicable to the development, prototyping, testing, and verification of the PMT High-Voltage Base circuit board.

1.3 Precedence

In the event of a conflict between the provisions of this document and any prior IceCube documents, the provisions of this document shall govern. Conflicts with other documents are resolved by the Change Control Board.

1.4 Responsibilities

1.4.1 Physics/Engineering is responsible for writing and updating these requirements to ensure they are correct, complete and current.

1.4.2 Quality Assurance is responsible for ensuring this document and changes to it are properly reviewed, approved and maintained.

1.5 Records

Records of initial review, approval and changes (Engineering Change Notices, ECN's) in design shall be maintained according to the established processes.

1.6 Units

Weights and measures in this document are expressed in the MKS International System of Units (SI).

1.7 Glossary and Acronyms List

ADC	Analog-to-Digital Converter
AWG	American Wire Gauge
cm	Centimeter
CMOS	Complementary Metal Oxide Semiconductor
CS0	Chip-select bit 1
CS1	Chip-select bit 0
DAC	Digital-to-Analog Converter
DAQ	Data Acquisition System
DC	Direct Current

DOM	Digital Optical Module
DOMMB	Digital Optical Module Main Board
ERD	Engineering Requirements Document
HV	High Voltage
Hz	Hertz
IDC	Insulation Displacement Connector
IPC	Institute for Interconnecting and Packaging Electronic Circuits
k	Kilo (10^3)
kg	Kilogram
LED	Light-Emitting Diode
MKS	Meter-kilogram-second
M	Mega (10^6)
m	Meter
mA	Milliampere
MOSI	Master-Out-Slave-In
MISO	Master-In-Slave-Out
mV	Millivolt
mW	Milliwatt
n	Nano (10^{-9})
OD	Outside Diameter
OM	Optical Module
Pa	Pascal
PCB	Printed circuit board
PE	Photoelectron
pF	Pico farad
PMT	Photomultiplier tube
P/V ratio	Peak-to-valley ratio
s, sec	Second
SCLK	Serial Clock
SI	Système International d'Unités
SPE	Single photoelectron
<i>TBD</i>	<i>To Be Determined</i>
UL	Underwriters Laboratory
V	Volt
VDC	Volt DC
W	Watt

1.8 References

- IceCube DOM Main Board – PMT HV Base Board Interface Requirements
- DOM Main Board ERD

2 FUNCTIONAL OVERVIEW

The photo-multiplier tube high-voltage base (PMT HV Base) board is a modular PCB component to be integrated into each of the approximately 5000 optical modules (OM), containing a photo-multiplier tube (PMT), that will be deployed in the Antarctic deep-ice (below several kilometers) for scientific research purposes. The PMT referred to in this document is a **Hamamatsu Model 7081-02** with a nominal size of 10 inches (25.4 cm) in diameter and a nominal gain of 10^8 .

The PMT HV Base board is required to function continuously without service over the entire twenty-year span of the research project under the deep-ice condition. See **3.4 Environmental**.

The PMT HV Base board has physical and electrical connections inside the OM with the photo-multiplier tube (PMT) and the digital optical module (DOM) main board (MB), the latter serving as the master controller of the entire OM. **Figure 2.1** depicts the functional relationship among the PMT HV Base board, the DOMMB and the PMT. **Table 2.1** summarizes the electrical connections between the PMT HV Base Board and the DOM Main Board.

The purpose of the PMT HV Base board is to facilitate the following functions:

1. Generate the series of high-voltages that are necessary to operate the PMT, using the power provided by the DOMMB.
2. Transfer the anode signal pulses from the PMT to the DOMMB without distortion through a coaxial cable.
3. Respond to the digital control commands issued by the DOMMB for power on/off and for adjustment of the high voltages.
4. Provide a digital reading of the high voltages to the DOMMB upon request.
5. Provide digital board identification information to the DOMMB upon request.

The physical installation of the PMT HV Base board is accomplished by inserting the PMT lead pins into the plated-thru holes and soldering. This also establishes the electrical connections between the PMT and the PMT HV Base board.

Detailed functional and performance requirements are specified in the rest of the document.

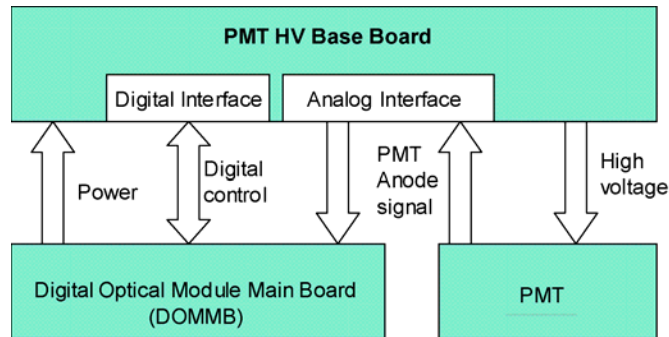


Figure 2.1 Functional overview of the PMT HV Base board.

Table 2.1 Summary of electrical connections requirements

Connection method	Explanation	Section
Plated-thru mounting holes	The board is physically mounted to the PMT by soldering the pins to these holes, which also makes electrical connections.	3.2.4
Coaxial RG-180B/U or equivalent	Connection between the secondary of the anode signal coupling transformer and the DOM main board. The board shall be delivered with one end of the coaxial cable attached to it.	3.2.3
1mm-pitch IDC Ribbon cable	Digital signals DC power Power & digital ground A female connector is required on board.	3.2.5.2
0.52 mm ² (20 AWG) stranded wire	“Clean ground” connection. The board shall provide a wire pad.	3.2.2.1.E

3 PERFORMANCE REQUIREMENTS

3.1 The HV PMT Supply

3.1.1 General

This subsection specifies electrical requirements applicable to the HV PMT supply portion of the PMT HV Base Board.

3.1.1.1 Note on requirements alternatives

A set of alternative requirements, replacing the requirements defined in **Section 3.1.4**, shall be issued at a later date as a supplement to this ERD. The vendor of the PMT HV Base board shall be appropriately notified by IceCube as to whether the present requirements or the said alternative requirements are to be enforced.

3.1.1.2 HV Generation

The method of HV generation shall be compatible with all the requirements stated in this document. In particular, the electrical impedance of the voltage sources for the individual dynodes must be sufficiently low in order to meet the anode current sourcing capability (3.1.5).¹

3.1.1.3 Definition

- (a) “**First dynode voltage**” shall refer to the voltage between the cathode and the first dynode of the PMT.
- (b) “**Anode voltage**” shall refer to the voltage between the first dynode and the anode of the PMT.

3.1.2 Dynode Chain Voltage Distribution²

3.1.2.1 Dynodes

The voltage across the successive dynode stages shall be according to the values specified in

Table 3.1 in which the values are expressed in terms of a factor to be multiplied with the voltage across Dynode 1 (first dynode) and Dynode 2.

3.1.2.2 Focusing electrodes

The voltage for the focusing electrodes, denoted as F1 – F3, shall also be determined by the factor specified in

Table 3.1, multiplied by the voltage across Dynode 1 and Dynode 2.

3.1.3 Damping Resistor Requirements

3.1.3.1

A 100 Ω (5% or better) resistor shall be present between each one of the last dynodes (Dy8, Dy9 and Dy10) and the corresponding high-voltage sources.

3.1.3.2

The said damping resistors shall be installed at locations easily accessible for the IceCube engineers to shunt or replace after the PMT HV Base board has been mounted on the PMT.

Table 3.1 Dynode chain voltage distribution (“Dyn” denotes the n-th dynode or Dynode n. “Fn” denotes the n-th focusing electrode.)

Interval	Voltage relative to Dy1 - Dy2
Dy2 - Dy3	1.25
Dy3 - Dy4	0.83
Dy4 - Dy5	0.42
Dy5 - Dy6	0.25
Dy6 - Dy7	0.30
Dy7 - Dy8	0.38
Dy8 - Dy9	0.55
Dy9 - Dy10	0.75
Dy1 - F1	0.15
Dy1 - F2	0
Dy1 - F3	0.15

3.1.4 HV Control

3.1.4.1 HV controllability requirements

3.1.4.1.A First dynode voltage

- The first dynode voltage shall be set to the factory default value of **700 VDC**.
- There shall be a provision for changing the said factory default value after delivery by the IceCube personnel to a value in the range of **600 to 800 VDC**, using a readily-accessible and reliable method, such as installing or replacing a resistor.

3.1.4.1.B Anode voltage

The anode voltage (first dynode-to-anode voltage) shall be adjustable at least over the range of **1000 to 2000 VDC** by means of a suitable digital code written to the DAC residing on the PMT HV Base board.³

3.1.4.2 HV monitoring requirement

There shall be a provision for monitoring the first dynode voltage and the anode voltage each as a separate digital

code of an ADC reading transmitted to the DOM main board.⁴

3.1.4.3 Digital interface

3.1.4.3.A DAC resolution

The DAC(s) used for setting the HV shall have a resolution of 12-bit.

3.1.4.3.B ADC resolution

The ADC(s) used for monitoring the HV shall have resolution of 12-bit.

3.1.4.3.C Digital code vs HV⁵

- (a) The digital code for setting and monitoring the HV shall be in 12-bit unsigned straight binary with the digital value 000(hex) representing 0 V.
- (b) The digital value and the corresponding HV value shall have a linear relationship at least in the voltage range specified in **3.1.4.1** with the slope of 0.5 V per bit.

3.1.5 Anode Current Sourcing Capability⁶

The HV generator of the PMT HV Base board shall support the following current sourcing capability in the sense that the output voltage does not drop more than 10 V while producing the specified current:

- (a) DC anode current of 12 nA at -40°C (deep-ice).
- (b) DC anode current of 240 nA at room temperature (laboratory).
- (c) Square-pulse anode current of 100 mA lasting for 1 μsec .

3.1.6 Stability

The drift rate for the voltages supplied to the dynodes and the anode shall be less than 4 V / week during the regular in-ice operation.⁷

3.1.7 Noise

The ripple voltage observed at the output of the secondary of the anode signal coupling transformer shall be no greater than 0.5mVpp when the output is terminated with a 100 Ω resistor.⁸

3.2 Electrical

3.2.1 Power

3.2.1.1

The PMT HV Base circuit board shall receive the electrical power from the DOM Main Board through the ribbon cable connector specified in **3.2.5.2**.

3.2.1.2

The power source available to the PMT HV Base circuit board shall be a ± 5 VDC voltage source with a voltage uncertainty of $\pm 5\%$.

3.2.1.3

The maximum power dissipation of the PMT HV Base board shall be 150 mW.

3.2.2 Ground

3.2.2.1 Split ground configuration

3.2.2.1.A Definitions

The PMT HV Base board shall have two isolated ground planes as defined below (See **Figure 3.1**):

- (a) **Digital and power ground** shall be referenced by the incoming power from the DOM Main Board; the digital control and monitor circuitry including ADCs and DACs; and, the regulator and switching circuitry for HV generation.
- (b) **Clean analog ground** shall be referenced by the voltage multiplier, dynode resistive divider, and regulator feedback circuitry.

3.2.2.1.B Isolation resistance

The two ground planes defined above shall have a minimum isolation resistance of 10 M Ω .

3.2.2.1.C Stray capacitance

The stray capacitance between the two ground planes shall be less than 50 pF.

3.2.2.1.D Jumper requirement

The PMT HV Base board shall have a provision for a solderable jumper (a zero-ohm resistor) between the two ground planes. The installation of the jumper is optional and shall be decided by the IceCube engineers after the delivery.⁹

3.2.2.1.E Wire soldering pad requirement

The PMT HV Base Board shall have a wire soldering pad for the purpose of attaching a 20 AWG (0.52 mm² conductor area) stranded wire for the “clean analog ground” connection to the DOM Main Board.

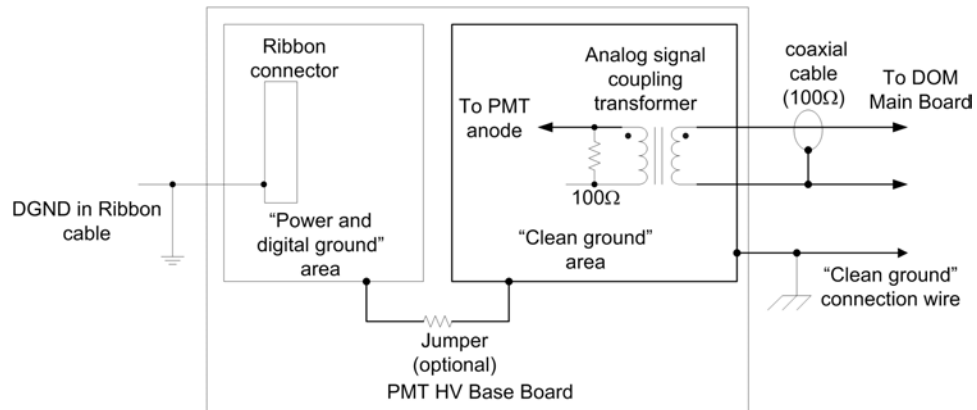


Figure 3.1 Split ground configuration requirement

3.2.3 Anode Signal Connection Requirements

3.2.3.1 Signal coupling method

The PMT HV Base board shall employ a coaxial toroidal transformer in order to deliver the PMT signal pulses to the DOM main board.

3.2.3.1.A Transformer signal definition

The transformer shall consist of a coaxial cable wound around a toroidal magnetic core.

- (a) The center conductor and the shielding conductor of the coaxial winding shall provide the primary winding and the secondary winding of the transformer, respectively.
- (b) The primary conductor and the secondary conductor accessible at one end of the coaxial winding shall be designated as the “dotted side” of the terminals (See **Figure 3.2**).

3.2.3.1.B Transformer specification

- (a) The transformer shall consist of a coaxial cable wound nineteen (19) times around a toroidal magnetic core.
- (b) The said coaxial cable shall be RG-178/U or RG-178B/U with a teflon inner dielectric and a teflon outer jacket.
- (c) The said toroidal magnetic core shall be Magnetics Model ZH-42206-TC (www.mag-inc.com) or equivalent.

- (d) Adequate spacing between the windings shall be provided in order to insure high-voltage isolation integrity.
- (e) There shall be an adequate means to hold the windings in place (such as a plastic plug pressed into the toroidal center, or a “belly-band” around the transformer).

3.2.3.1.C Primary side requirements¹⁰

- (a) The primary side of the coaxial transformer shall be terminated with a 100Ω resistor across the primary terminals (“back termination”).
- (b) The “dotted” side of the primary terminal shall connect to the PMT anode terminal.
- (c) The “un-dotted” side of the primary terminal shall connect to the source of the anode high-voltage.

3.2.3.1.D Secondary side requirements¹¹

- (a) The secondary side of the coaxial transformer shall be connected to the DOM Main Board using a coaxial medium.
- (b) The said coaxial medium shall be RG-180B/U or a similar coaxial cable with a characteristic impedance of 100Ω.
- (c) The center conductor and the shield conductor of the said coaxial cable shall connect to the “dotted” side and the “un-dotted” side of the secondary terminal of the transformer, respectively.



Figure 3.2 Anode signal coupling transformer signal definition (Illustration purpose only. See text for correct winding requirements).

3.2.3.1.E Coaxial cable installation requirement

The PMT HV Base Board shall be delivered with the coaxial cable specified in **3.2.3.1.D** installed.

- (a) Electrical connections of the coaxial cable shall be accomplished by direct soldering.¹²

- (b) The said electrical connections shall not degrade when the cable is pulled with a maximum of 5kg of force in any directions.
- (c) The length of the coaxial cable shall be $30 \pm 1\text{cm}$.
- (d) No special treatment shall be required of the unattached end of the coaxial cable.

3.2.4 PMT Mounting Holes Requirements

3.2.4.1 Plated-thru PMT mounting holes and soldering pads

3.2.4.1.A

The PMT HV Base board shall have plated-thru holes specified in **Figure 3.3** in order to make electrical connections to the PMT.

3.2.4.1.B

Each of the said plated-thru holes shall have an annular soldering pad in the manner specified in **Figure 3.4**.

3.2.4.1.C

The locations of the said plated-thru holes on the PCB are as specified in .

3.2.4.2 Signal assignment to the PMT mounting holes¹³

3.2.4.2.A

The electrical signal assignment to the plated-thru PMT mounting holes are as shown in **Figure 3.3** and **Figure 3.7**.

3.2.4.2.B

The PMT signals defined shall be assigned to the said solder pads according to the arrangements specified in .

3.2.4.2.C

The PMT HV board shall not be required to have holes to accommodate the pins that are assigned "No connection".

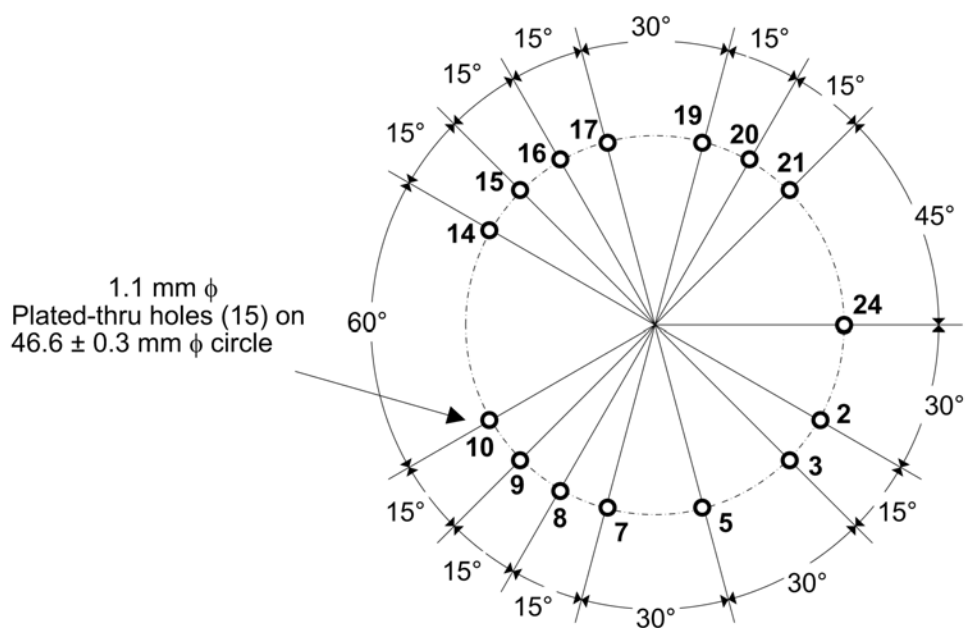


Figure 3.3 Plated-thru PMT mounting hole locations viewed from the top-side of the PMT HV Base circuit board. The numerical labels associated with the holes mark the corresponding PMT pin number.

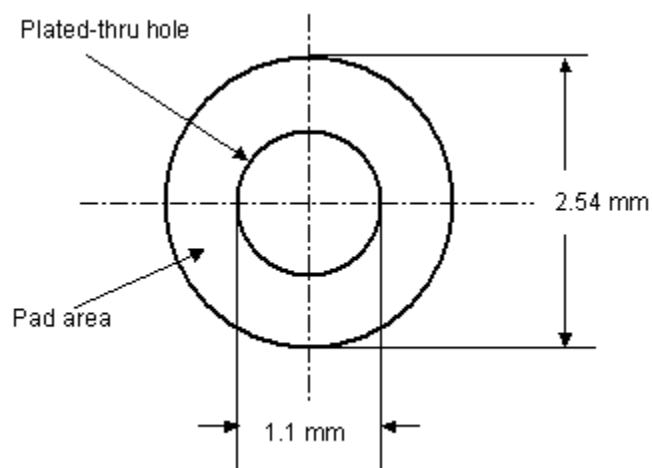


Figure 3.4 Solder pad specification

Table 3.3 PMT Pin Assignment

Pin #	Signal name	Description
01	NC	No connection

02	Dy1	Dynode #1
03	F3	Focus #3
04	NC	No connection
05	Dy3	Dynode #3
06	NC	No connection
07	Dy5	Dynode #5
08	Dy7	Dynode #7
09	Dy9	Dynode #9
10	P	Anode
11	NC	No connection
12	NC	No connection
13	NC	No connection
14	Dy10	Dynode #10
15	Dy8	Dynode #8
16	Dy6	Dynode #6
17	Dy4	Dynode #4
18	NC	No connection
19	Dy2	Dynode #2
20	F1	Focus #1
21	F2	Focus #2
22	NC	No connection
23	NC	No connection
24	K	Cathode

3.2.5 Digital Functionality Requirements

3.2.5.1 Digital signal standard

3.2.5.1.A The digital signals (logic levels and voltages) between the PMT HV Base board and the DOM main board shall comply with the **3V CMOS** signal standard.

3.2.5.1.B The PMT HV Base Board shall *not* rely on the 5V-tolerance of the DOM Main Board when transmitting a signal.

3.2.5.2 The ribbon cable

The PMT HV Base Board shall have electrical connections with the DOM Main Board through a ribbon cable, defined in this section, for the following purposes:

- Power and ground connections
- Digital signal connections

3.2.5.2.A The ribbon cable type

The ribbon cable shall be a 1mm-pitch flat IDC ribbon cable.

3.2.5.2.B The ribbon connector type¹⁴

The PMT HV Base board shall have a 2mm-pitch female IDC-type connector for the ribbon cable at the location specified in **Figure 3.8**.

3.2.5.2.C Signal duplication requirement

Each signal, ground and power in the ribbon cable shall have two connector pins allocated to it.

3.2.5.2.D Ribbon connector signal assignment

The signal assignment to the ribbon connector pins shall be as defined in **Table 3.6**.

3.2.5.3 Chip-select (CS0, CS1)

The two chip-select signals, CS0 and CS1, shall be used in combination to select one of the following three digital devices residing on the PMT HV Base board:

- DAC: Digital-to-analog converter
- ADC: Analog-to-digital converter
- IDENT: Board identification device (**3.2.5.6**)

3.2.5.3.A The assignment of the logic levels to CS0 and CS1 shall be determined by the vendor of the PMT HV Base board.

3.2.5.4 MOSI, MISO and SCLK signals

- DAC shall use MOSI and SCLK for data and serial clock, respectively.
- ADC shall use MISO and SCLK for data and serial clock, respectively.
- IDENT shall use one or more of MOSI, MISO and SCLK.

3.2.5.5 Power ON/OFF Control**3.2.5.5.A**

The PMT HV Base board shall support a power ON/OFF control by the DOM Main Board through the ribbon cable.

3.2.5.5.B

The signal assignment for the power ON/OFF control shall be as shown in **Table 3.4**.

3.2.5.5.C

Power-up default When the PMT HV Base board is turned on, the HV output shall be consistent with the DAC digital code of 0x000 (See **3.1.4.3.A**).

Table 3.4 Power ON/OFF signal assignment

Logic Level	Meaning
0	OFF
1	ON

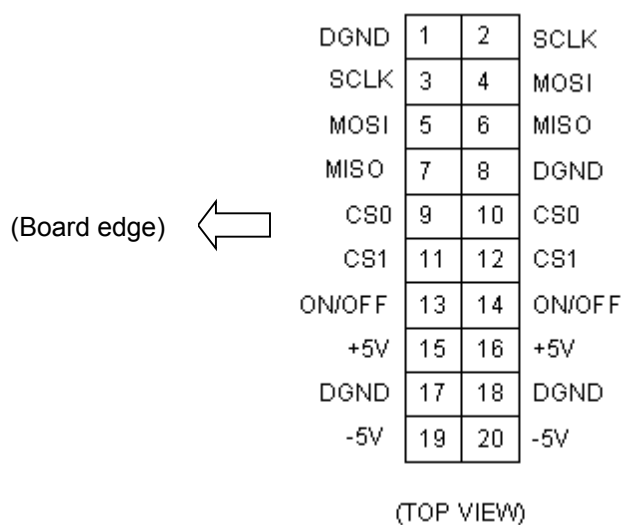
3.2.5.6 Digital Board Identification

3.2.5.6.A

The PMT HV Base board shall provide a unique digital board identification number (board ID) upon request from the DOM main board.

3.2.5.6.B

The said digital board ID device shall comply with the Dallas 1-Wire protocol to communicate with DOMMB serving as the bus master.¹⁵

**Figure 3.5** Ribbon connector signal assignment**Table 3.6** Ribbon connector signal assignment

Pin #	Signal Name	Description
01	DGND	Digital and power ground
02	SCLK	Serial clock
03	SCLK	
04	MOSI	Master-out-slave-in
05	MOSI	

06	MISO	Master-in-slave-out
07	MISO	
08	DGND	
09	CS0	Chip-select bit 0 (See)
10	CS0	
11	CS1	Chip-select bit1 (See)
12	CS1	
13	ON/OFF	Board enable/disable
14	ON/OFF	
15	+5V	Main power (+)
16	+5V	
17	DGND	
18	DGND	
19	-5V	Main power (-)
20	-5V	

3.3 Physical

3.3.1 Definition

The “**bottom side**” of the PMT HV Base board shall refer to the side of the PCB from which the PMT leads are inserted. The “**top side**” of the PMT HV Base board shall refer to the side opposite to the bottom side. The terms “**top view**” and “**bottom view**” shall refer to the views from the top side and the bottom side of the PMT HV Base board, respectively.

3.3.2 Overall size and shape requirements¹⁶

The overall shape of the printed circuit board of the PMT HV Base shall be circular and no larger than **100 mm** in diameter. A greater diameter or a deviation from the circular outline for accommodation of special components such as connectors and cable harnesses shall be permitted provided that there is sufficient clearance between such components and the interior surface of the pressure vessel of the optical module. The dimensional requirements are summarized in **Figure 3.7** and **Figure 3.8**. The volume constraints shall apply to both of the mating pieces of the ribbon connectors.

3.3.3 Component placement

The components may be placed on either the top side or the bottom side of the PCB within the constraints of the component envelope, except for the following items, whose locations are specified in **Figure 3.8**:

- (a) Anode signal coupling transformer (Bottom side)
- (b) Coaxial cable for the anode signal connection
- (c) Ribbon cable connector (Bottom side.)

- (d) “Clean ground” connection wire pad

The following items shall be installed at locations where IceCube engineers can easily access for modification after the PMT HV Base board has been mounted on the PMT:

- (e) Damping resistors (3.1.3)
(f) Solder pads for the optional jumper (3.2.2.1.D)

3.3.4 Excluded area

No components shall be mounted in the areas so specified in Figure 3.8.

3.3.5 Minimum trace spacing requirements¹⁷

In compliance with the circuit board trace layout rules specified for “B-4 External Conductors with Permanent Polymer Coating” in IPC-2221, §6.3 Electrical Clearance, the following conditions shall be met for both DC voltages and AC peak voltages:

- For voltage difference greater than 100 V and less than 300 V, the minimum trace spacing shall be 0.4 mm.
- For voltage difference greater than 300 V and less than 500 V, the minimum trace spacing shall be 0.8 mm.
- For voltage difference greater than 500 V, the minimum trace spacing shall be 0.8 mm plus 0.00305 mm per every volt exceeding 500 V.

3.3.6 Manual soldering compatibility¹⁸

The PCB shall be compatible with the increased temperature during the manual soldering of the PMT pins at the solder pads specified in 3.2.4.

3.4 Environmental

3.4.1 Temperature Range¹⁹

3.4.1.1 Operation

The continuous operating temperature of the PMT HV Base board shall be in the range of **–55°C to +27°C**.

3.4.1.2 Storage

The storage temperature for the PMT HV Base board shall be in the range of **–55°C to +45°C**.

3.4.2 Pressure Range

The PMT HV Base circuit board shall be capable of operating continuously inside the pressure vessel with the sustained internal pressure of **40,000 Pa to 100,000 Pa**.

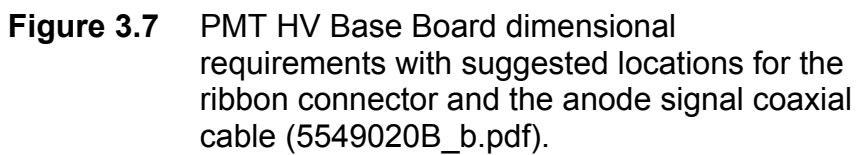
3.5 Miscellaneous

3.5.1 Conformal coating

Conformal coating is required on both sides of the PCB. Areas where soldering will be performed after delivery shall be properly masked from the conformal coating.

3.5.2 Silkscreen

Silkscreen is required on the top side of the PCB.



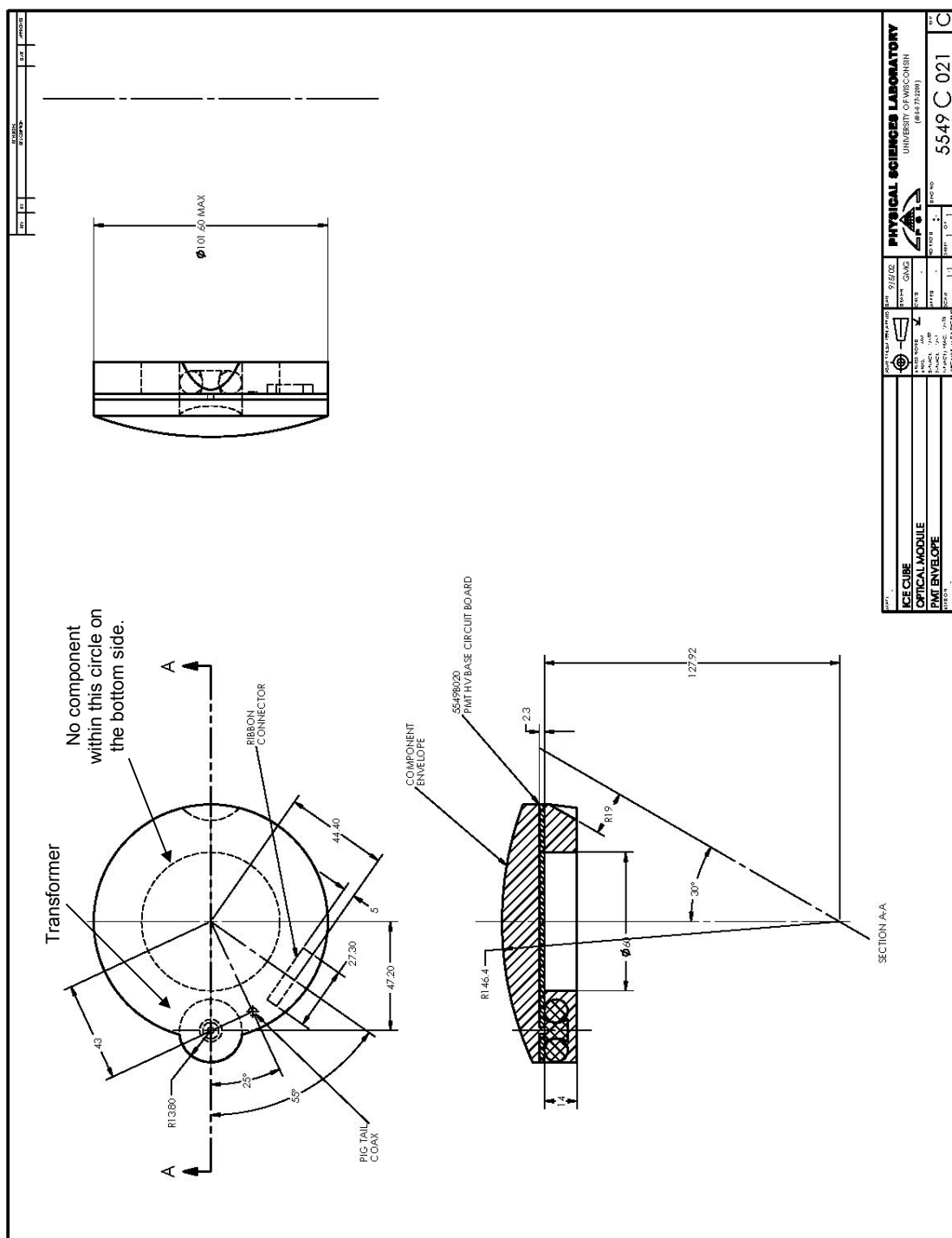


Figure 3.8 PMT HV Base Board dimensional requirements (5549021C_c.pdf).

Appendix 1 Design Notes

3.1.1.2 HV Generation

¹ **Justification:** Reference to a Cockcroft-Walton type generator in the earlier versions of this document has been removed in order to avoid unnecessary constraints on sound technical solutions.

3.1.2 Dynode Chain Voltage Distribution

² **Note:** The voltage ratios are in accordance with the specification for **Hamamatsu PMT Model R7081-02**.

3.1.4.1 HV controllability requirements

³ **Justification:** The first dynode voltage mainly controls the peak-to-valley ratio (P/V ratio), whereas the anode voltage mainly controls the gain of the PMT. Once the first dynode voltage is set to a value corresponding to an adequate P/V ratio (greater than 2.2), the voltage should not require readjustment. It is possible to set the first dynode voltage to be sufficiently high so that the P/V ratio always exceeds the minimum required value of 2.2, regardless of the parameter variations among the PMTs. The PMT (Hamamatsu R7081-02) has a nominal operating voltage of 460V for the first dynode voltage. The manufacturer of the PMTs, however, confirms that the first dynode voltage may be as high as 800V without adverse effects. See the e-mail exchange between Kael Hanson and Yuji Yoshizawa, Application and Sales Engineer of Hamamatsu Photonics Electron Tube Center. The latest correspondence from Yoshizawa also confirms and guarantees that the cathode-to-anode voltage may be raised to 2000V, rather than previously-stated 1800V, thereby allowing a greater gain adjustment range (i.e., 2000V minus first-dynode voltage).

3.1.4.2 HV monitoring requirement

⁴ **Justification:** It is useful to be able to read the exact state of the HV. The ADC resolution should meet the DAC resolution.

3.1.4.3 Digital interface

⁵ **Justification:** High-performance ADCs and DACs are readily available with 12-bit resolution. A 12-bit resolution, corresponding to 0.5 volt per bit, is adequate for both monitoring and setting the HVs.

3.1.5 Anode Current Sourcing Capability

⁶ **Justification:** The DC current requirement is obtained by assuming the PMT gain of $5E7$, the average number of photoelectrons giving rise to the anode pulse of 1.5, and the noise rate of 1 kHz in deep-ice and 20 kHz at room temperature (worst case). The pulse current requirement is meant to assure the dynamic range supporting all pulses that are realistically possible in the ice. (The Hamamatsu PMT supports up to 70 mA of anode current and we don't want the PMT Base board to be the bottleneck of any physical measurements.)

3.1.6 Stability

⁷ **Justification:** The gain-voltage relationship of the PMT is a power law of the form $G \sim V^B$, where B ranges from 8 to 10, depending on the PMT. Assuming the worst case with B=10, a 2% change in gain would require a voltage stability of $dV/V = (1/B)(dG/G) = 0.2\%$, and consequently, a dV of several volt.

3.1.7 Noise

⁸ **Justification:** The rule of thumb being applied is that the trigger threshold for the system should be about $1/6^{\text{th}}$ of the amplitude of an SPE (5mV), and that the systematic noise should be a small contribution to the triggering at that threshold.

3.2.2.1 Split ground configuration

⁹ **Justification:** The optimum ground connections for noise immunity need to be determined experimentally in conjunction with the DOM main board. The split ground configuration is prerequisite for noise immunity. The jumper requirement allows flexibility for experimentation.

3.2.3.1.C Primary side requirements

¹⁰ **Note:** It is vital that the anode signal connection is made with the correct signal polarity.

3.2.3.1.D Secondary side requirements

¹¹ **Justification:** This RG-180B/U cable has a characteristic impedance of 95Ω . The output impedance of the transformer circuit is approximately 100Ω , and the output pulse from the anode circuit suffers the least distortion when driving the same impedance.

3.2.3.1.E Coaxial cable installation requirement

¹² **Justification:** It is desirable to have the fewest number of solder connections after delivery. The stripping and soldering of the thin coaxial cable is a potential quality issue. Direct soldering is more preferable than using a connector for reliability and cost reasons.

3.2.4.2 Signal assignment to the PMT mounting holes

¹³ **Justification:** The pin assignments are consistent with the pinouts for Hamamatsu PMT Models R7081-01 and R7081-02. The plated-thru hole and solder pad dimensions are similar to those for the AMANDA 1999 Tube Base. The PMT supplier (Hamamatsu) has agreed to deliver the PMT with the "No connection" pins cut short or removed.

3.2.5.2 The ribbon cable

¹⁴ **Justification:** The 1mm-pitch cable is consistent with a 2mm-pitch ribbon connectors. These connectors are more space-saving than the traditional 2.54mm-pitch counterpart.

3.2.5.6 Digital Board Identification

¹⁵ **Note:** A recommended device for this purpose is a Dallas Semiconductor DS2401.

3.3.2 Overall size and shape requirements

¹⁶ **Justification:** Constraints on the size of the PMT HV Base board arise from the envelope of the Benthos glass sphere; the depth of the PMT placement in the optical gel; the envelope of the PMT itself;

and, the position of the sphere penetrator. The mounted height of the PMT HV Base board above the PMT has been chosen to be 20 mm. The drawings provided are intended to make available a generous volume for the PMT HV Base board. The 11-inch PMT has been ruled out due to size constraints in favor of the 10-inch PMT. The 100mm-overall diameter is met by the current Iseg prototype.

3.3.5 Minimum trace spacing requirements

¹⁷ **Justification:** These rules are necessary to ensure a reliable high-voltage performance. The rules assume that the conductor traces are on the outer layers of the PCB and that a permanent polymer overcoat (post-assembly conformal coating) is present.

3.3.6 Manual soldering compatibility

¹⁸ **Note:** Hamamatsu specifies the soldering conditions as less than 3 sec at 250°C at 10mm from the glass. The PCB may undergo a greater level of heating without exceeding the Hamamatsu spec, since the board is to be mounted 20mm from the PMT glass.

3.4.1 Temperature Range

¹⁹ **Justification:** The ice-top temperature of –52°C and deep-ice temperature of –40°C are expected for operation. The higher upper limit for the storage temperature takes care of possible situations during transportation.